

GNS3 Documentation

v0.4

Parts of this tutorial are taken from the excellent Dynagen tutorial by Greg Anuzelli.

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Introduction

GNS3 is a graphical network simulator that allows you to easily design network topologies and then run simulations on them. At the moment GNS3 supports IOS routers, ATM/Frame Relay/Ethernet switches and PIX firewalls. You can even extend your own network by connecting it to your virtual topology.

To do his magic, GNS3 is based on Dynamips, Pemu (including its wrapper) and in part on Dynagen, it has been developed in python and through [PyQt](#) the GUI part is made with the powerful [Qt library](#), famous for its use in the [KDE](#) project. GNS3 also uses the [SVG technology](#) (Scalable Vector Graphics) to provide high quality symbols for designing your network topologies.

About Dynamips

Dynamips is a Cisco router emulator written by Christophe Fillot. It emulates 1700, 2600, 3600, 3700, and 7200 hardware platforms, and runs standard IOS images. In Chris' own words:

This kind of emulator would be useful to:

- *Be used as a training platform, with software used in the real world. It would allow people to become more familiar with Cisco devices, Cisco being the world leader in networking technologies;*
- *Test and experiment features of Cisco IOS;*
- *Check quickly configurations to be deployed later on real routers.*

Of course, this emulator cannot replace a real router, it is simply a complementary tool to real labs for administrators of Cisco networks or people wanting to pass their CCNA/CCNP/CCIE exams.

Although Dynamips provides a simple virtual switch, it **does not emulate Catalyst switches** (although it does emulate the NM-16ESW).

About Dynagen

Dynagen is a text-based front end for Dynamips written by Greg Anuzelli which provide a separate OOP API used by GNS3 for interfacing with Dynamips. GNS3 also uses the Dynagen INI-like configuration file format and integrates Dynagen's management CLI which allows users to list devices, suspend and reload instances, determine and manage idle-pc values, perform packet captures, and more.

If somehow you have stumbled upon this tutorial without first finding the GNS3, Dynamips or Dynagen web sites, here they are along with some other important links:

GNS3: <http://www.gns3.net/>

Dynamips: http://www.ipflow.utc.fr/index.php/Cisco_7200_Simulator

Dynamips Blog (where most of the action is): <http://www.ipflow.utc.fr/blog/>

Dynagen (a text-based front-end to the emulator): <http://dyna-gen.sourceforge.net/>

GNS3 / Dynamips / Dynagen Bug tracking: <http://www.ipflow.utc.fr/bts/>

Hacki's Dynamips / Dynagen / GNS3 Forum: <http://7200emu.hacki.at/index.php>

Installing GNS3

GNS3 runs on Windows, Linux and Mac OS X (other platforms not tested) and requires the following dependencies to be installed if you want to use it from a source archive:

- Qt >= 4.3, available on <http://trolltech.com/developer/downloads/qt/index>
- Python >= 2.4, available on <http://www.python.org>
- Sip >= 4.5 if you need to compile PyQt, available on <http://www.riverbankcomputing.co.uk/sip>
- PyQt >= 4.1 available on <http://www.riverbankcomputing.co.uk/pyqt>

We have also put together an all-in-one Windows installer package that includes Winpcap, Dynamips, Pemuwrapper, and a compiled version of GNS3, eliminating the need to install Python, PyQt and Qt. It also provides Explorer "integration" so you can double-click on network files in order to run them.

Windows users should install the all-in-one Windows installer package. This provides everything you need to run GNS3 on local or remote machines, except an IOS and PIXOS image (see the next section).

Linux users should download Dynamips and extract it to a suitable location. Install the GNS3 dependencies and then run GNS3. Users on Debian/Ubuntu can install the

python-qt4 package or follow the instructions on <http://gpl.code.de/oswiki/GplcodedeApt> in order to install a GNS3 .deb package.

Note: If you are running Dynamips on a RedHat or Fedora system, take a look at Dynamips [FAQ item #2](#) if you are experiencing segfaults when you try to run Dynamips.

At the moment, Mac OS X users have to manually compile the dependencies. A binary version should be released soon.

Here is a little procedure to install the required dependencies on Mac OS:

1. Install the Apple Devs Tools (on your Mac OS X DVD or download it from an ADC account). You just need to install XcodeTools.mpkg in order to have gcc, make etc.
2. (Only on Tiger – 10.4.x) Download python 2.5.2 for MacOS X on <http://www.python.org/download/> and install it.
3. Download qt-mac-opensource-4.3.4.dmg on <http://trolltech.com/developer/downloads/qt/mac> and install it.
4. Download SIP on <http://www.riverbankcomputing.co.uk/sip/>, compile and install it
\$>python ./configure
\$>make
\$>sudo make install
5. Download PyQt <http://www.riverbankcomputing.co.uk/pyqt/>, compile and install it (you will need to comment OpenGL lines in the Makefile if the compilation fail).
\$>python ./configure
\$>make
\$>sudo make install

IOS Images

Dynamips runs real Cisco IOS images. From the Dynamips FAQ:

Can you provide a Cisco IOS image for a 7200 to me?

No, I am not allowed to distribute IOS images. You will have to find one by yourself. This should not be a problem if you are a Cisco customer.

On Windows, drop the image in C:\Program Files\Dynamips\images. You can actually drop the images anywhere you want, but the sample labs are configured to look

here. On Linux/Unix systems, designate a location to store your images and drop them there (I like to use /opt/images, but it's your system.)

Cisco IOS images are compressed. These compressed images will work just fine with Dynamips*, however the boot process is slowed significantly by this decompression process (just like on real routers). It is recommended that you decompress the images beforehand, so the emulator doesn't have to. You can do this with the "unzip" utility on Linux/Unix/Cygwin as follows:

```
unzip -p c7200-g6ik8s-mz.124-2.T1.bin > c7200-g6ik8s-mz.124-2.T1.image
```

You will receive a warning from unzip, which you can safely ignore. On Windows you can use WinRAR to uncompress images. You may download a free copy of WinRAR at <http://www.winrar.com>.

Note that currently images for 1700 and 2600 routers must be uncompressed to work with Dynamips.

Please, always test your IOS image directly with Dynamips before using it in GNS3:

```
./Dynamips -P <chassis> <path-to-the-ios-image>
```

Resource Utilization

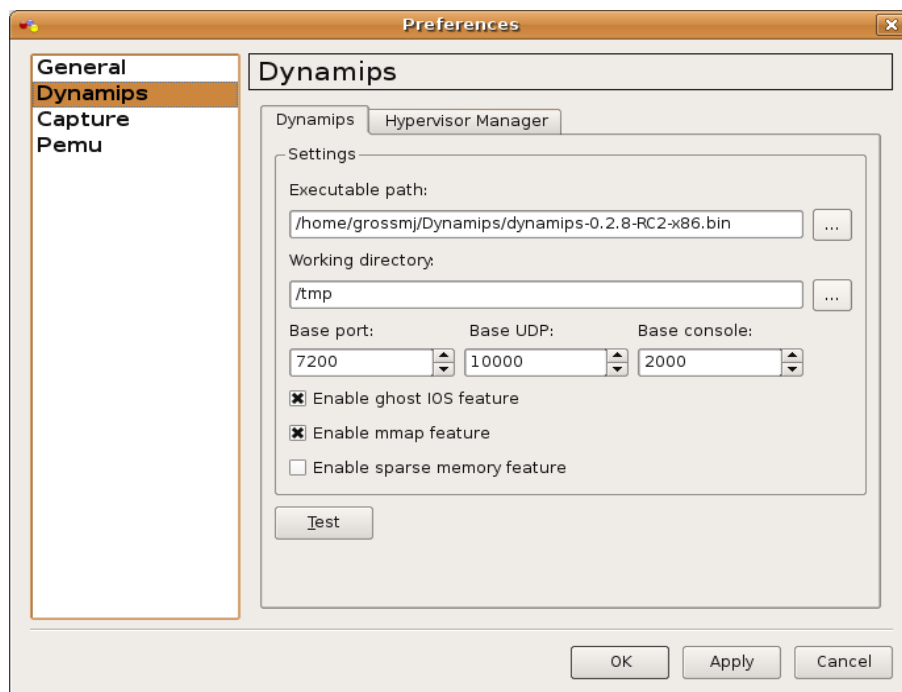
Dynamips uses a fair amount of RAM and CPU in order to accomplish its emulation magic. If you intend to run an IOS image that requires 256 MB of RAM on a real 7200 router, and you devote 256 MB of RAM to your virtual router instance, it will allocate 256 MB of working set memory. Dynamips also allocates (by default) 64 MB of RAM per instance on Unix systems (16 MB on Windows systems) to cache JIT translations. This will be the total working set size; by default the amount of your system's actual RAM used will typically be significantly less. This is because, by default, Dynamips uses memory mapped files for the routers' virtual memory. In the working directory you will see temporary "ram" files equal to the size of the virtual routers' RAM size. Your OS will naturally cache in RAM the sections of the mmap files that are being used. (See the [Memory Usage Optimizations](#) section for configuration options that can significantly reduce memory utilization).

If you have plenty of RAM, and you know what you are doing, uncheck “Enable mmap feature” in the Dynamips preferences.

Dynamips also uses a lot of CPU power, because it is emulating a router’s CPU instruction-by-instruction. It initially has no way of knowing when the virtual router’s CPU is idle, so it dutifully executes all the instructions that make up the IOS’s idle routines - just as it would execute the instructions that perform “real” work. But once you have run through the “Idle-PC” process for a given IOS image, CPU utilization decreases drastically. More on this very important topic later.

Configuring Dynamips Preferences

To use Dynamips in GNS3, you must configure the path to it and the base port. These settings will be used by the Hypervisor Manager and to load .net files. Go to Preferences on the Edit menu:



The working directory is where all the files generated by Dynamips are stored, these include the NVRAM for the virtual router, as well as the bootflash, logfiles, and some other working files

Options:

- “Enable sparse memory feature” is to globally use (or not) the Dynamips's sparsemem feature (see Memory Usage Optimizations section for more details).
- “Enable mmap feature” is to globally use (or not) the Dynamips's mmap feature (see Resource Utilization section for more details).
- “Enable ghost IOS feature” is to globally use (or not) the Dynamips's ghost feature (see Memory Usage Optimizations section for more details)

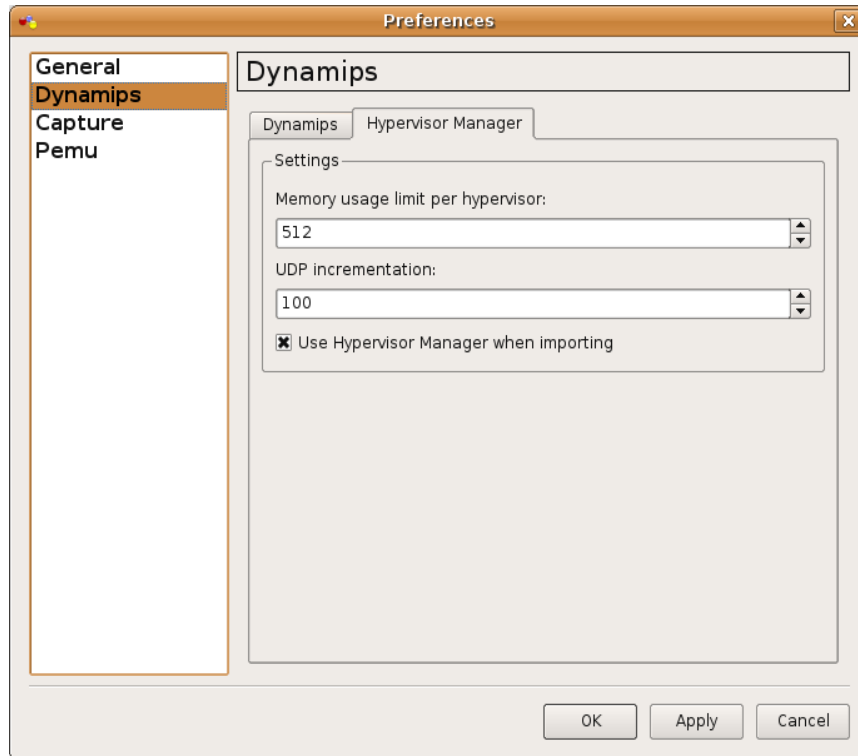
The Hypervisor Manager is used to run your hypervisors internally in GNS3, which means you don't need to start them manually. This manager also helps to address the memory usage limit per process problem when running many IOS instances on a single hypervisor (see FAQ to learn more about this issue) by “load-balancing” instances on multiple hypervisors.

Let's look at an example of how it works:

We want to run 5 IOS instances which uses 256 MB each and we configured the memory usage limit per hypervisor setting to 512 MB. When we start the lab, the hypervisor manager will create 3 hypervisor processes based on the following formula (you must round to the next highest whole number):

$$\text{number of hypervisors} = (256 * 5 / 512)$$

The Hypervisor Manager assigns the first 2 instances to the first hypervisor, the next 2 to the second hypervisor, and the last instance on the third hypervisor.



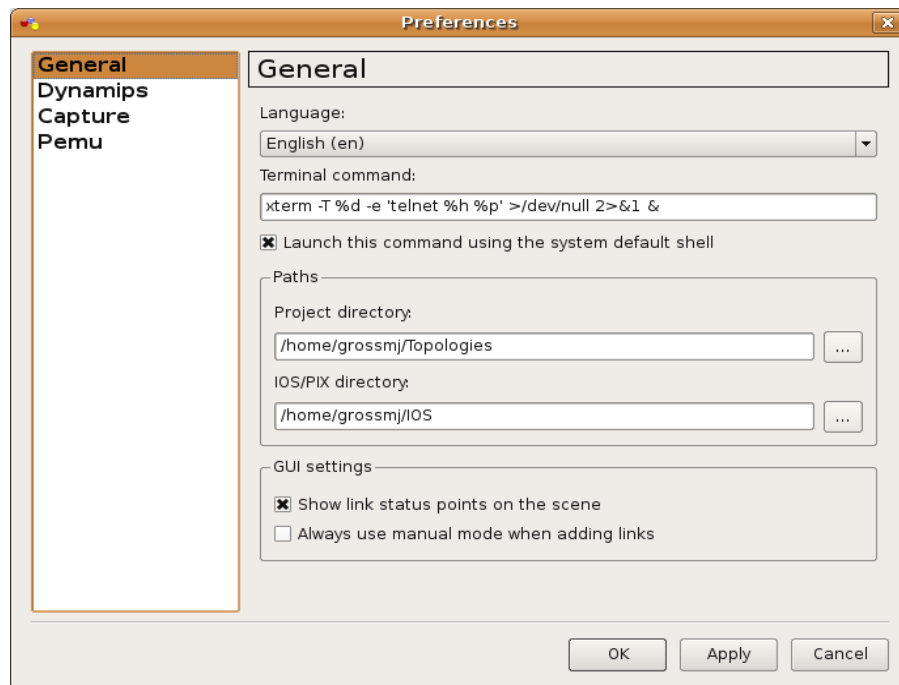
There are two other settings in the Dynamips preferences. “UDP incrementation” tells the hypervisor manager how to increment the Dynamips base udp port for each hypervisor process created (so if the base udp port is 10000 in Dynamips preferences and the incrementation is 100, then for 3 hypervisors this will set the base udp to 10000 for the first hypervisor, 10100 for the second and so on).

Note: more information on UDP issues can be found in the “Client / Server and Multi-server Operation” section.

The option “Use the hypervisor manager when importing” is used when loading a topology file (.net) in GNS3. If this option is checked and in the .net file you have defined hypervisors to run on localhost, then GNS3 considers that those hypervisors need to be started by the Hypervisor Manager. If not checked, those hypervisors are recorded as external hypervisors and must be manually started.

Configuring General Preferences

To allow you to connect to the virtual router consoles, you also must configure the terminal command.



GNS3 will propose you a default command but you can set a custom one.

The following substitutions are performed:

%h = host

%p = port

%d = device name

You have the choice to launch your command through a shell (cmd.exe by default on Windows or any command line interpreter set in %COMSPEC% environment variable).

Terminal Command Examples

- On Windows (without cmd.exe):

TerraTerm SSH users: `C:\Program Files\TTERMPRO\ttssh.exe %h %p /W=%d /T=1`

PuTTY users: `C:\Program Files\PuTTY\putty.exe -telnet %h %p`

SecureCRT users: start C:\Program
Files\SecureCRT\SecureCRT.EXE /script c:\Program
Files\dynamips\securecrt.vbs /arg %d /T /telnet %h %p & sleep 1

- On Linux:

Gnome users: gnome-terminal -t " + name + " -e 'telnet " +
host + " " + str(port) + "' > /dev/null 2>&1 &

- On Mac OS X:

With Terminal: /usr/bin/osascript -e 'tell application
"Terminal" to do script with command "telnet %h %p ; exit"' -e
'tell application "Terminal" to tell window 1 to set custom
title to "%d"'

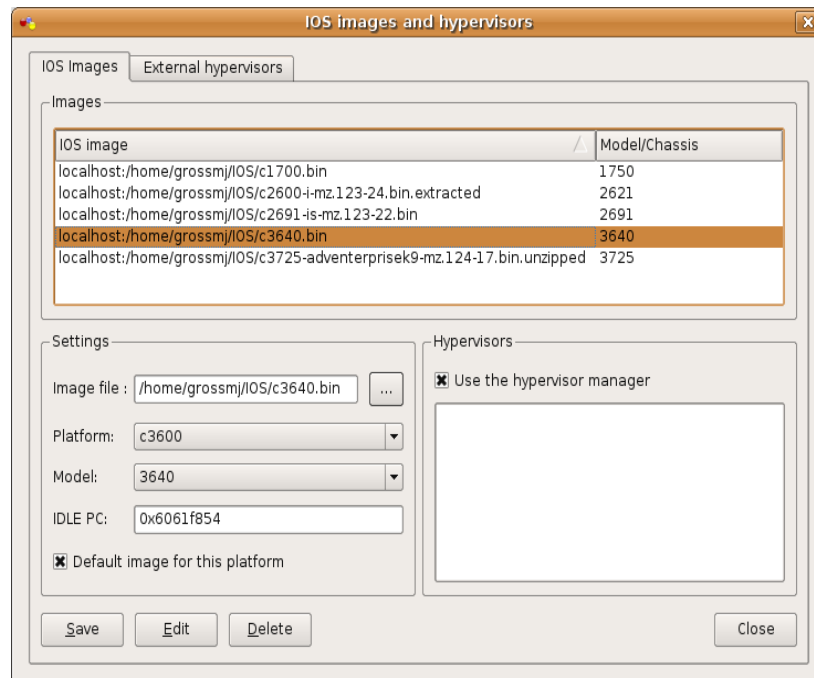
With iTerm with named tabs: /usr/bin/osascript -e 'tell app
"iTerm"' -e 'activate' -e 'set myterm to the first terminal' -e
'tell myterm' -e 'set mysession to (make new session at the end
of sessions)' -e 'tell mysession' -e 'exec command "telnet %h
%p"' -e 'set name to "%d"' -e 'end tell' -e 'end tell' -e 'end
tell'

Running a simple lab

In this section we are going to guide you on how to run a three routers lab step-by-step.

Once GNS3 is started and if it is the first time you run it please see “Configuring Dynamips Preferences” section.

First you have to record at least one IOS image by selecting Edit -> IOS images from the menu (or pressing CTRL + SHIFT + I). Then set the path to an IOS image, choose the platform and the chassis (if applicable) and input an IDLE PC value if you have it. By default, you are using the integrated hypervisor (the dynamips processes managed by GNS3) to run your IOS.

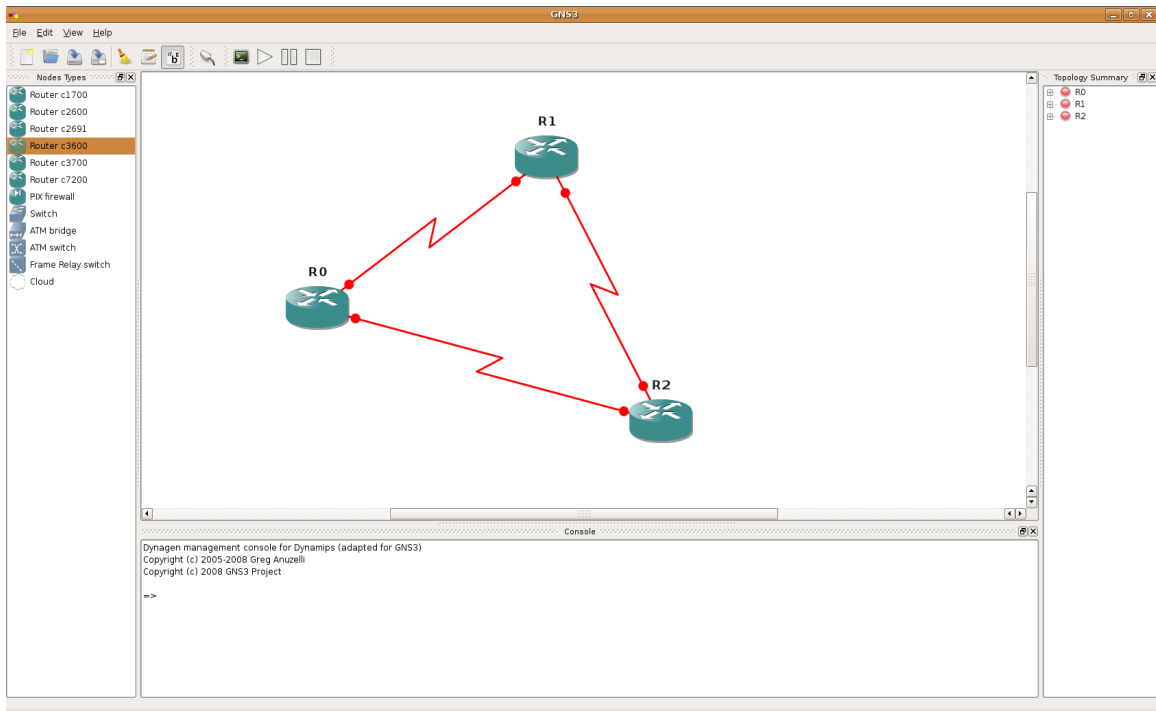


If you want to use external hypervisors (started by yourself), you can record them in the “Hypervisors” tab (see the “Client / Server and Multi-server Operation” section for more information).

All of these indicated IOS systems and hypervisors are saved in your gns3.ini file, so you just have to record them once.

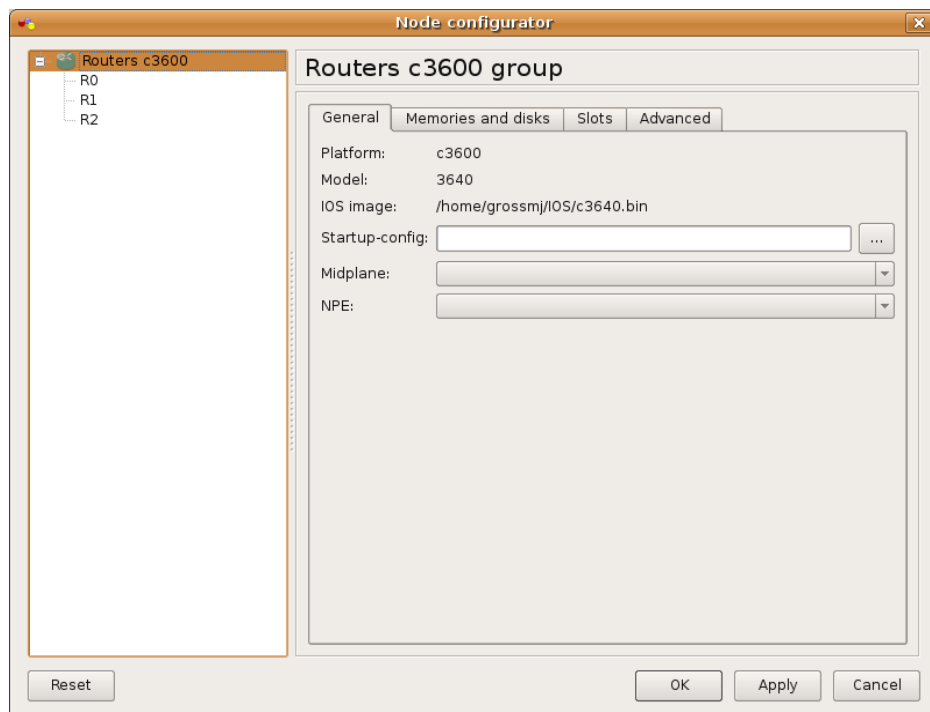
Note: the gns3.ini file is located in %APPDATA% or %COMMON_APPDATA% on Windows and \$HOME/.gns3/ or /etc/gns3/ on Linux/Unix.

Now you can create your network topology by drag 'n' dropping nodes from the list on the left to the scene on the right.



Once your topology is created, you may configure your nodes (right-click a node and choose configure).

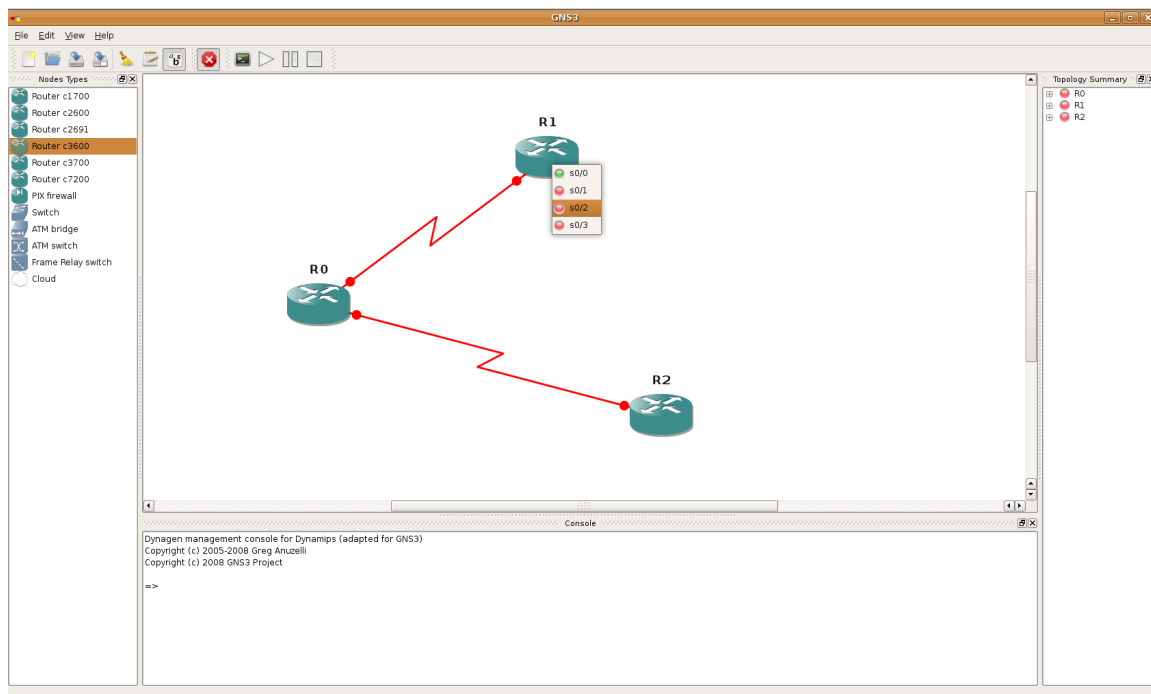
You may apply the same settings for every router by selecting “Routers” in the left tree or for specific routers by selecting their hostname in the tree.



In the node configurator you can select the IOS to use and configure many other things like the startup-config, the RAM size, the slots etc.

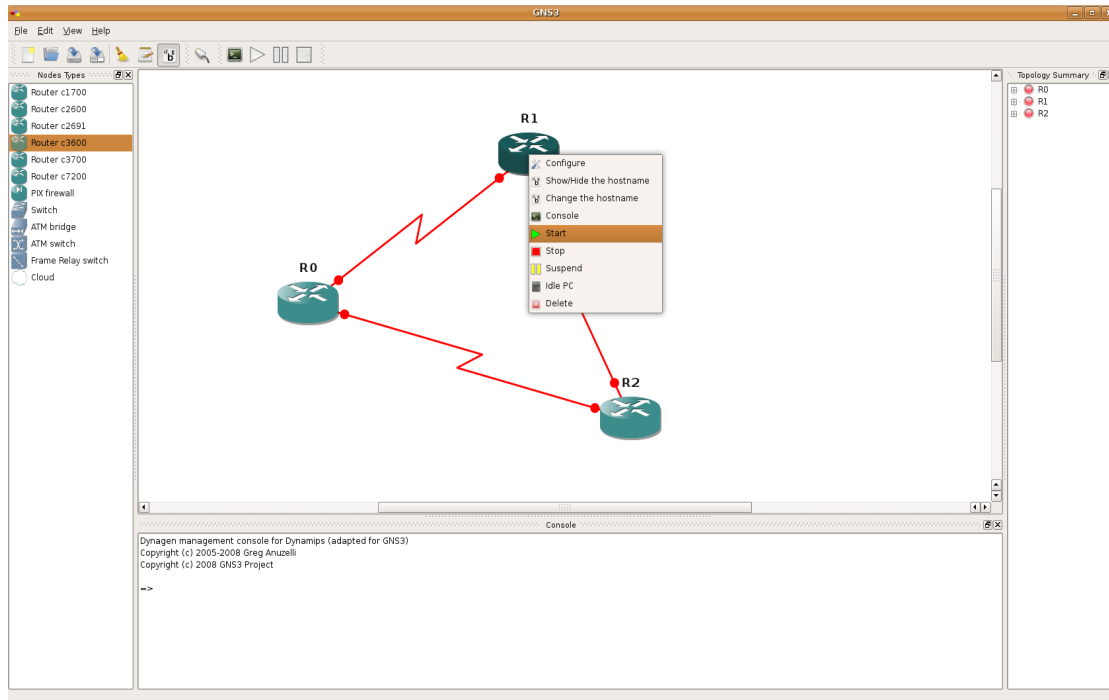
Next, add links between your nodes (click the “Add a link” button on the menu bar, select your source node and then your destination node). You will notice that you can choose the type of link (Ethernet, serial ...). If you do GNS3 assigns automatically the right modules for your corresponding link type in the slots of your routers and chooses the first available interface to connect the link.

You may manually choose the interface to connect your link by choosing the manual method from the drop-down menu. But keep in mind that you must then configure the slots on your routers manually as well.



Note: used interfaces are marked in green; unused interfaces are marked in red.

Your network topology with all settings is then created on the hypervisor(s). You can start/stop/suspend an IOS instance by right-clicking on a node. If you have started the IOS, you may also go to a console session for the device. Note: multiple nodes may be selected in order to perform the operation on those nodes at the same time.

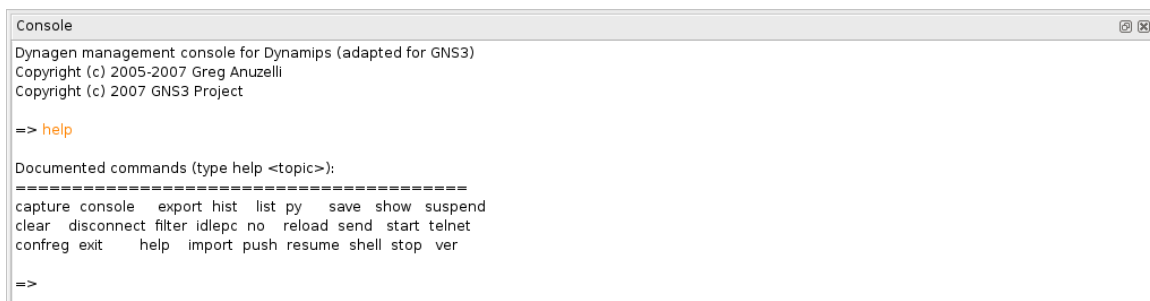


Once connected with by console to your routers, you can assign appropriate IP addresses to the serial interfaces (you can see the connected interfaces by looking at the topology summary on the right or by letting your mouse hover over a link), and “no shut” them, because they are indeed connected.

Working with the Console

Note: the Console pane at the bottom is only available when you are in emulation mode.

From the Console, use the **help** command to see a list of valid commands:



To get help on a particular command, either type **help *command*** or ***command* ?**. For example:

```
Console
==> help

Documented commands (type help <topic>):
=====
capture console export hist list py save show suspend
clear disconnect filter idlepc no reload send start telnet
confreg exit help import push resume shell stop ver

==> help confreg
confreg {/all | router1 [router2] <0x0-0xFFFF>}
set the config register(s)
==>
```

To “power off” a virtual router, use the **stop** command. Help shows the syntax as:

```
stop {/all | router1 [router2] ...}
```

To shut down a single router, type **stop *routername***:

```
Console
Documented commands (type help <topic>):
=====
capture console export hist list py save show suspend
clear disconnect filter idlepc no reload send start telnet
confreg exit help import push resume shell stop ver

==> help confreg
confreg {/all | router1 [router2] <0x0-0xFFFF>}
set the config register(s)
==> stop R1
100-VM 'R1' stopped
==>
```

And sure enough, the router is now stopped:

```
Console
confreg exit help import push resume shell stop ver

==> help confreg
confreg {/all | router1 [router2] <0x0-0xFFFF>}
set the config register(s)
==> stop R1
100-VM 'R1' stopped
==> list
Name   Type   State   Server      Console
R0     7200   running localhost:7200 2000
R1     7200   stopped localhost:7200 2001
R2     7200   stopped localhost:7200 2002
==>
```

You can also provide a **list** of routers to stop, or issue **stop /all** to shut down all router instances.

To restart R1, use the **start** command:

```
start {/all | router1 [router2] ...}
```



```
Console
confreg {/all | router1 [router2] <0x0-0xFFFF>}
set the config register(s)
=> stop R1
100-VM 'R1' stopped
=> list
Name    Type    State    Server    Console
R0      7200    running  localhost:7200 2000
R1      7200    stopped  localhost:7200 2001
R2      7200    stopped  localhost:7200 2002
=> start R2
100-VM 'R2' started
=>
```

The IOS reload command is not supported by Dynamips in virtual routers. So you can use the console **reload** command. It performs a stop, followed by a start. To reload all routers in the entire lab, issue a **reload /all** command:



```
Console
R1      7200    stopped  localhost:7200 2001
R2      7200    stopped  localhost:7200 2002
=> start R2
100-VM 'R2' started
=> reload /all
100-VM 'R0' stopped
*** Error: router "R1" is already stopped
100-VM 'R2' stopped
100-VM 'R0' started
100-VM 'R1' started
100-VM 'R2' started
=>
```

The **suspend** and **resume** commands have a syntax similar to stop and start, but they temporarily pause the specified routers:


```
Console
=> suspend /all
100-VM 'R0' suspended
100-VM 'R1' suspended
100-VM 'R2' suspended
=> list
Name      Type      State      Server      Console
R0        7200      suspended  localhost:7200 2000
R1        7200      suspended  localhost:7200 2001
R2        7200      suspended  localhost:7200 2002
=> resume /all
100-VM 'R0' resumed
100-VM 'R1' resumed
100-VM 'R2' resumed
=> |
```

The **exit** command stops and deletes all devices from the network, and switches to design mode. If you exit the Console, your simulation will no longer be running.

Calculating Idle-PC values

You may have noticed that your previous simulations caused your system's CPU to peg at 100% and stay there. This is because Dynamips does not know when the virtual router is idle and when it is performing useful work. The "idlepc" command performs analysis on a running image to determine the most likely points in the code that represent an idle loop in IOS. Once applied, Dynamips "sleeps" the virtual router occasionally when this idle loop is executed, significantly reducing CPU consumption on the host without reducing the virtual router's capacity to perform real work.

Here is how the process is performed. First, create a single router corresponding to the IOS image you want to calculate its idlepc.

Then start your router and telnet to the running router instance. If you are presented with IOS autoconfig prompt, respond with "no".

```
R0
Trying 127.0.0.1...
Connected to localhost.
Escape character is '^]'.
Connected to Dynamips VM "R0" (ID 4, type c3600) - Console port

% Please answer 'yes' or 'no'.
Would you like to enter the initial configuration dialog? [yes/no]:
```

Wait for all of the interfaces to initialize. Then it enter to see the IOS prompt.

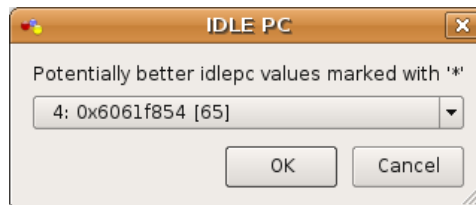
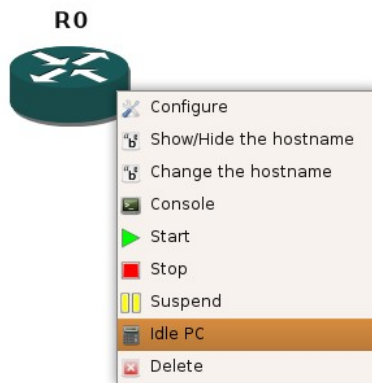
```
R0
Trying 127.0.0.1...
Connected to localhost.
Escape character is '^]'.
Connected to Dynamips VM "R0" (ID 4, type c3600) - Console port

% Please answer 'yes' or 'no'.
Would you like to enter the initial configuration dialog? [yes/no]: no

Press RETURN to get started!

*Mar  1 00:00:02.431: %LINEPROTO-5-UPDOWN: Line protocol on Interface VoIP-Mul10, changed state to up
*Mar  1 00:00:30.371: %SYS-5-RESTART: System restarted --
Cisco IOS Software, 3600 Software (C3640-IS-M), Version 12.3(8)T, RELEASE SOFTWARE (fc2)
Technical Support: http://www.cisco.com/techsupport
Copyright (c) 1986-2004 by Cisco Systems, Inc.
Compiled Thu 13-May-04 16:38 by eaarnas
*Mar  1 00:00:30.375: %SNMP-5-COLDSTART: SNMP agent on host Router is undergoing a cold start
Router>
```

Now, switch back to GNS3 do a right click on the router and select "Idle PC" You will see a screen that statistics are being gathered, and about 10 to 20 seconds later you should see a window which contains a list of potential idlepc values:



Values that will most likely provide better results are marked with an asterisk. Select one of the values to try from the menu and press the OK button. You should notice your host (the one running the dynamips process) CPU utilization drop dramatically. Then enter exit on the IOS console, the CPU utilization should not rise. If so, you've found a good idlepc value for this particular IOS image.

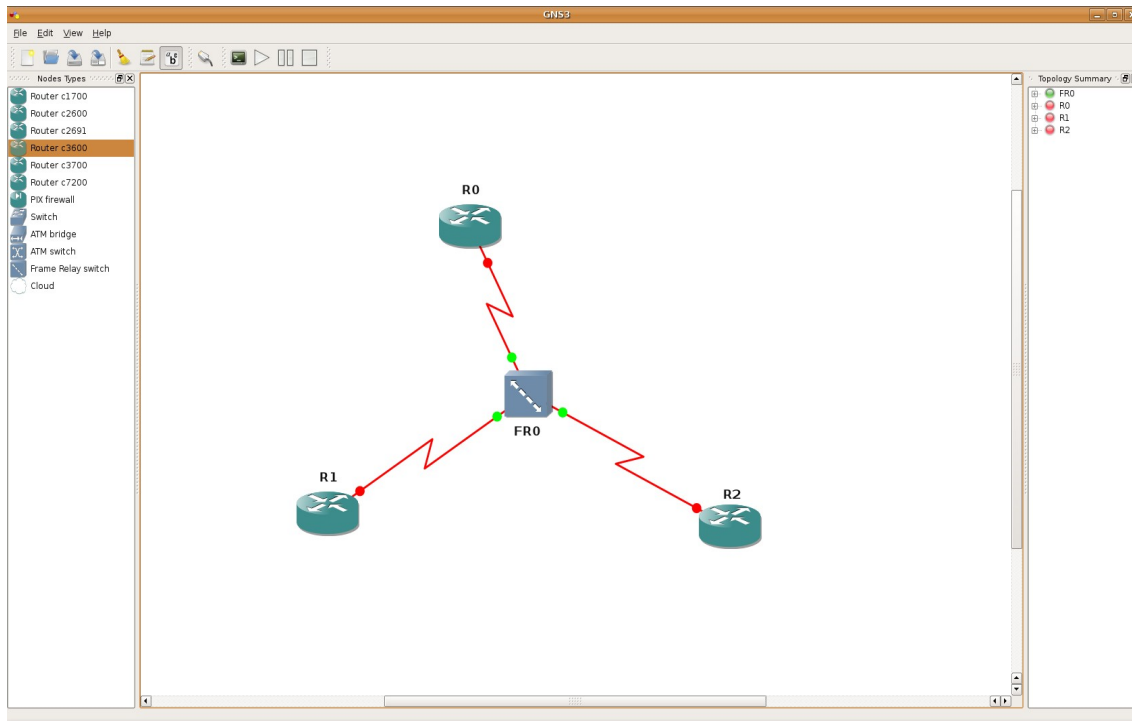
If your CPU usage did not drop, it's time to try a different value (do a right click on the router, you do not need to calculate the idle pc this time) and test again when logged and not logged.

Idle-PC values are particular to an IOS image. They will be different for different IOS versions, and even for different feature sets of the same IOS version. However Idle-PC values are not particular to your host PC, operating system, or to the version of dynamips.

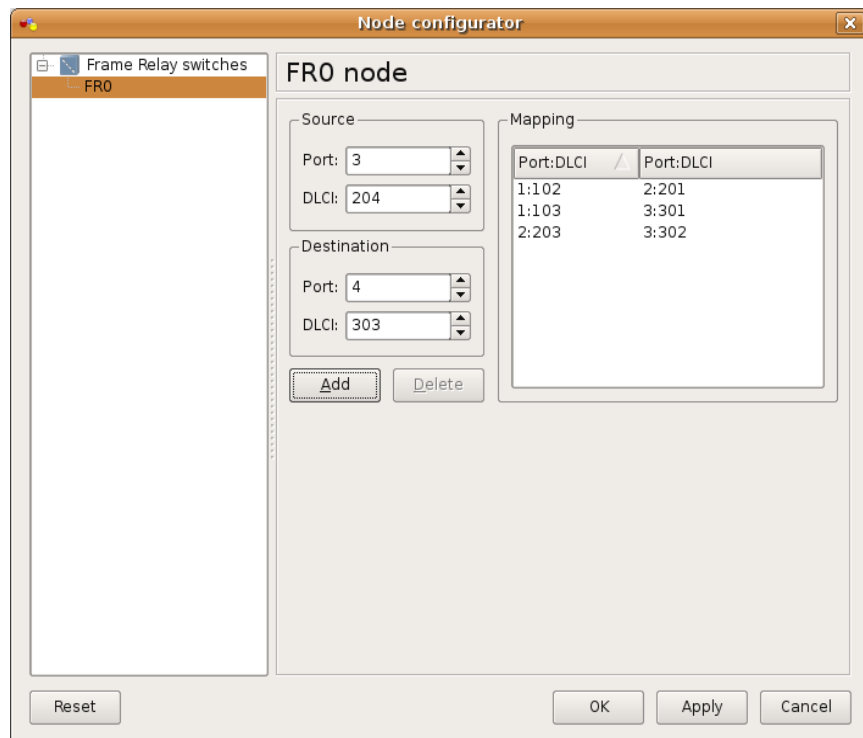
It is possible that dynamips will not be able to find and idlepc value for an image, or that the values it does find do not work. If this happens, try repeating the process again. Or you just might be out of luck with that particular image (however running into this situation is rare.)

Using a Frame Relay device

Dynamips (and accordingly GNS3) provides support for an integrated frame relay switch. Looking at a frame relay lab:



We have connected the routers' serial interfaces to ports 1, 2, and 3 respectively on a Frame Relay switch named "F0".



Through the Node configurator we assigned a local DLCI of 102 on port 1, which maps to a DLCI of 201 on port 2. The other two entries are configured similarly, thereby creating a full mesh of PVCs between the three routers. (103 <-> 301, and 201 <-> 302).

Note: The Frame Relay switch emulated by Dynamips uses an LMI type of ANSI Annex D, not Cisco.

Launching the lab shows the following:

```

Console
Dynamgen management console for Dynamips (adapted for GNS3)
Copyright (c) 2005-2007 Greg Anuzelli
Copyright (c) 2007 GNS3 Project

=> list
Name      Type    State    Server      Console
R0        7200    running  localhost:7200 2000
R1        7200    running  localhost:7200 2001
R2        7200    running  localhost:7200 2002
F0        FRSW    always on localhost:7200 n/a
=>

```

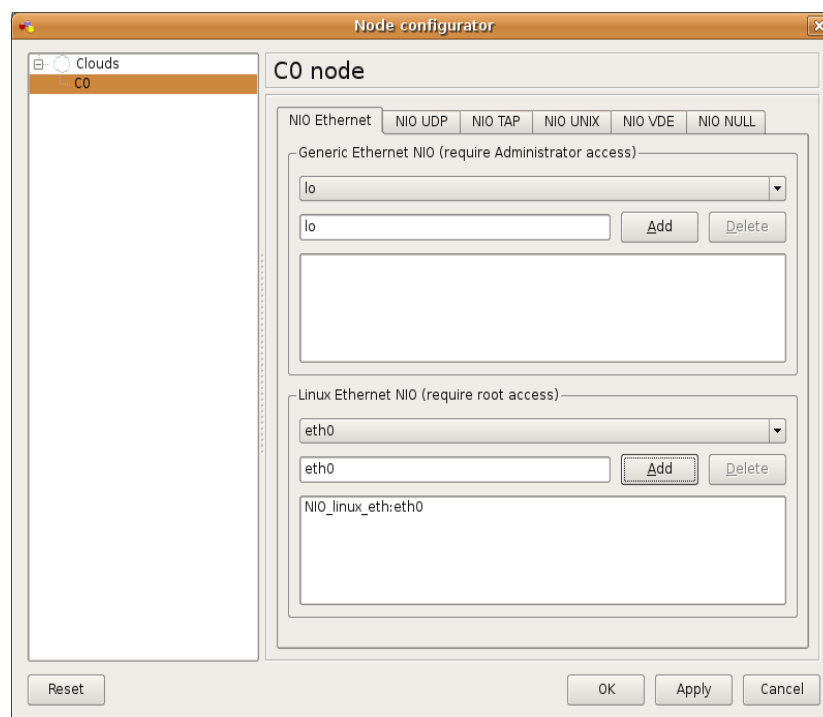
The Frame Relay switch F0 is listed, but you can't stop, start, suspend, or resume it like you can with virtual routers.

The ATM switch device can be configured in the same way.

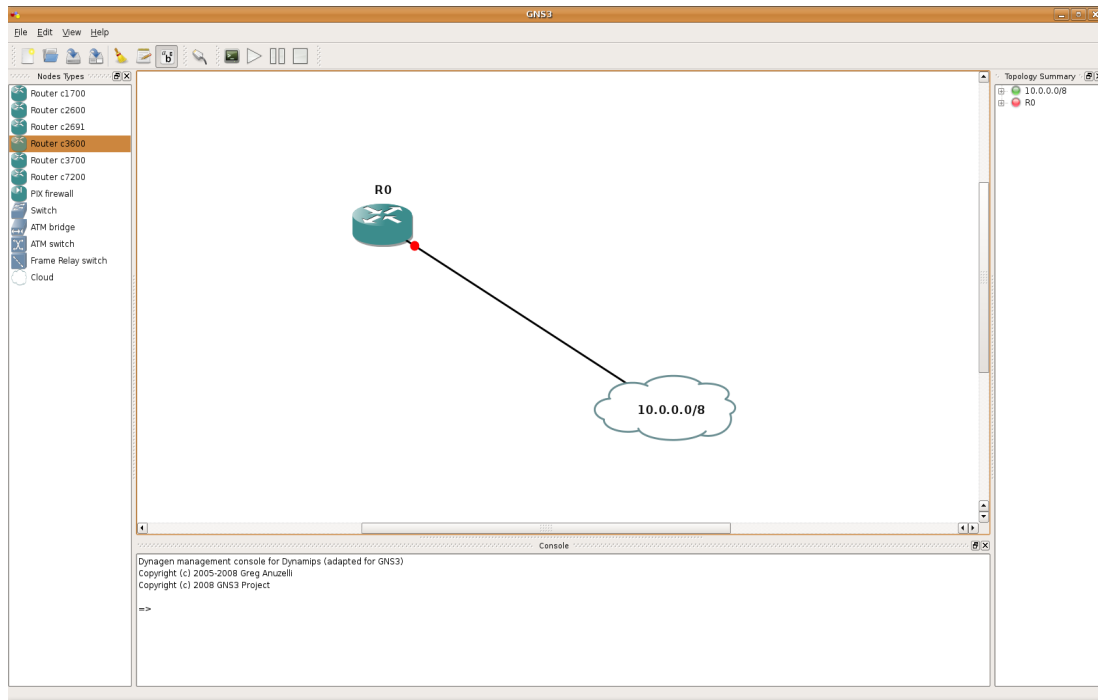
Communicating with Real Networks

Dynamips can bridge virtual router interfaces with real host interfaces, allowing your virtual network to communicate with the real world. On Linux systems, this is done with the NIO_linux_eth NIO (Network Input Output) descriptor.

To use this feature with GNS3 you must create a “Cloud” device. A cloud represents your external connections. Then you must configure it. In this example we added the NIO_linux_eth0 NIO:



Then you can connect your cloud to a router or a Ethernet switch. In the following image we bridged the router's e0/0 interface to the eth0 interface on the host. Packets that exit e0/0 are dumped out onto the real network through eth0, and return packets are forwarded back to the virtual router instance accordingly.



On Windows systems, the Winpcap library is used to accomplish this bridging. The interface format is a little more complex than on Linux systems. GNS3 will perform an auto-detection with the help of DynaMips to list the available interfaces. If the detection did not work, use the shortcut created by the GNS3 Windows installer (thanks to Dynagen). In program menu, open the “Network Device List” shortcut:

```
C:\ Network device list
Cisco 7200 Simulation Platform (version 0.2.6-RC2-x86)
Copyright (c) 2005,2006 Christophe Fillot.

Network device list:

  rpcap://\Device\NPF_GenericDialupAdapter : Network adapter 'Adapter for gener
ic dialup and UPN capture' on local host
  rpcap://\Device\NPF_{B00A38DD-F10B-43B4-99F4-B4A078484487} : Network adapter
'Broadcom NetXtreme Gigabit Ethernet Driver (Microsoft's Packet Scheduler)' on
local host
  rpcap://\Device\NPF_{92D96691-E307-444E-872B-F1609E942A78} : Network adapter
'VMware Virtual Ethernet Adapter' on local host
  rpcap://\Device\NPF_{662A24E7-88A3-4413-83DA-C3F84B7B8F8B} : Network adapter
'Bluetooth PAN Driver (Microsoft's Packet Scheduler)' on local host
  rpcap://\Device\NPF_{D1496ED7-03C5-4655-8A14-5418299C2E40} : Network adapter
'VMware Virtual Ethernet Adapter' on local host

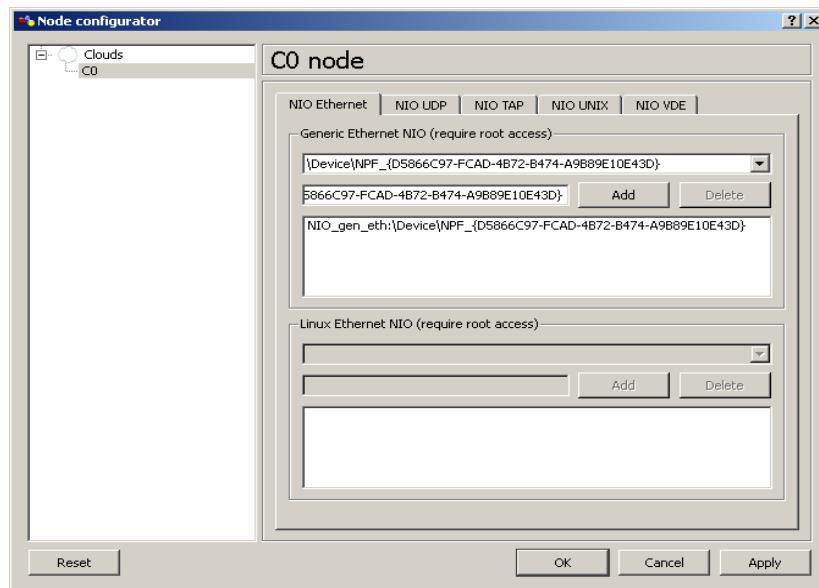
Use as follows:
  F0/0 = NIO_gen_eth:\Device\NPF_{...}

Press any key to continue . . . _
```

So on my Windows system, I would use:

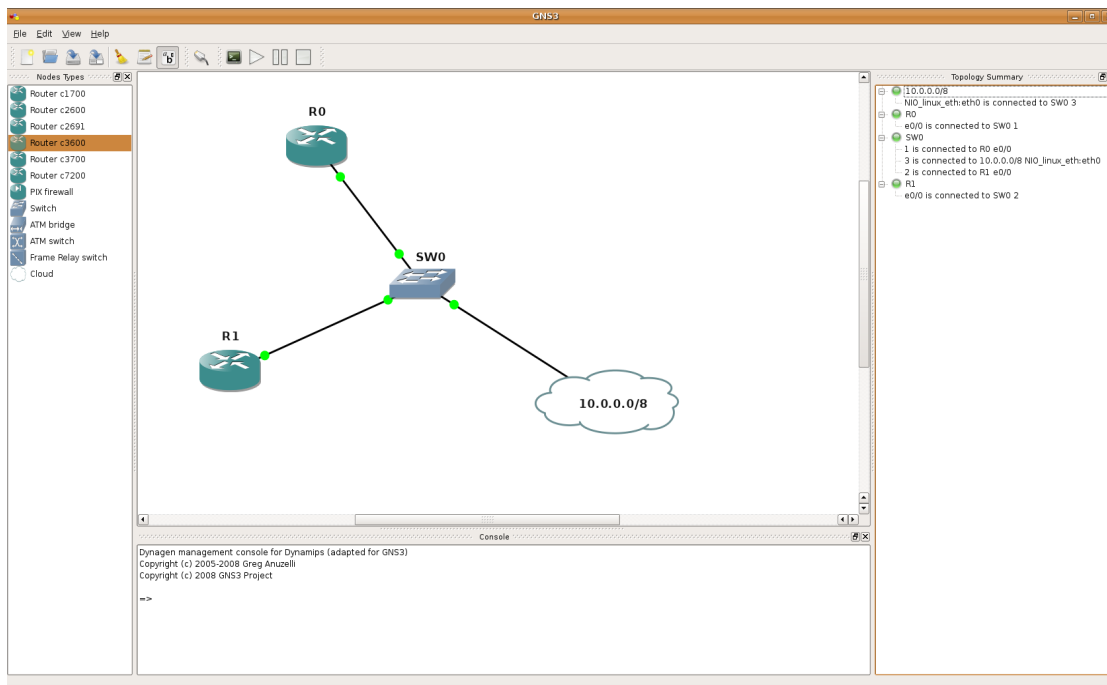
```
\Device\NPF_{B00A38DD-F10B-43B4-99F4-B4A078484487}
```

to bridge to my local Ethernet adapter. You just need to put this value in the Generic Ethernet NIO text box when configuring your “Cloud” device. Select the device from the drop down box, or paste it into the white box to the left of the Add button from the “Network Device List” shortcut. Then click the Add button to place the proper device into the white box below the Add button.

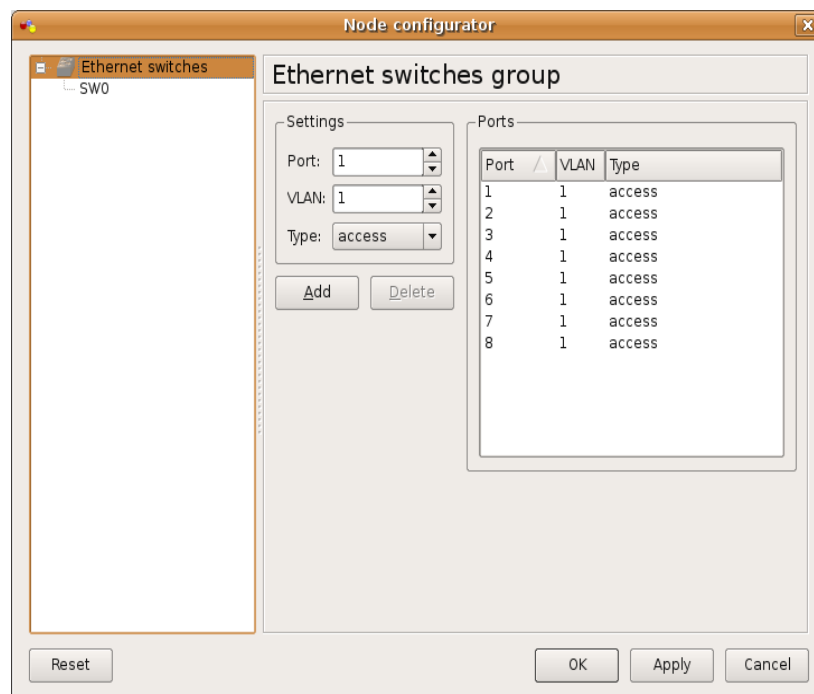


Using an Ethernet Switch device

Dynamips also provides an integrated virtual Ethernet switch that supports VLANs with 802.1q encapsulation. Looking at this lab:



Port 1 of the switch (connected to R1 e0/0) is an access port in VLAN 1. Port 2 is also an access port. Port 4 is a trunk port (specified with the dot1q keyword) with a native VLAN of 1. Trunk ports trunk all the VLANs known to the switch.



By default in GNS3, a switch has 8 access ports configured in VLAN 1.

You can also connect a switchport to the “real world” by connecting the switch to a “Cloud” device. Here we are connecting a trunk port (dotq1 encapsulation) with a native vlan of 1 to the host’s eth1, or Windows network device using the NIO_gen_eth Winpcap NIO (see Communicating with Real Networks section). If this host interface is connected to a real switch that is configured for trunking, you can now easily connect any router instance to any VLAN you wish.

The console includes CLI commands to show and clear the MAC address tables of virtual Ethernet switches. Those commands are **show mac *Ethernet_switch_name*** and **clear mac *ethenet_switch_name***.

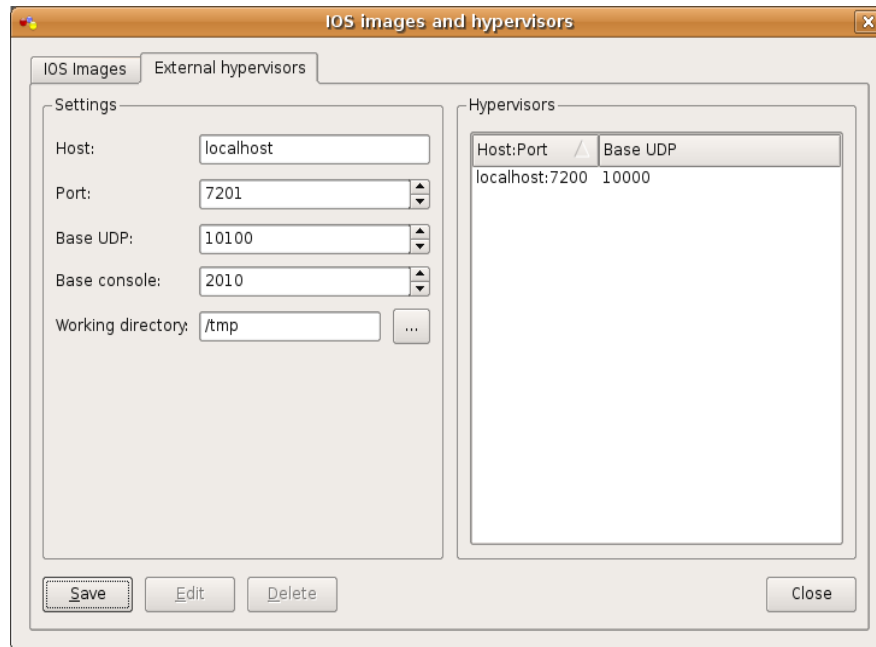
WIC Modules

Dynamips 0.2.8-RC1 added support for several WIC modules. Currently, these are the WIC-1T and WIC-2T on the 1700, 2600, 2691 and 3700 platforms, and the WIC-1ENET on the 1700. See the [Hardware Currently Emulated](#) section for specific model info and how many WIC slots are provided on each platform.

Note: In GNS3, once a WIC is inserted in a router, it cannot be removed.

Client / Server and Multi-server Operation

The Dynamips “Hypervisor” mode that is used by GNS3 is a TCP/IP communications channel, so GNS3 can run on a different machine than the Dynamips emulator. This is done by manually specifying a hypervisor in the “IOS images and hypervisors” window.



Here we recorded a new hypervisor which will listen on port 7200 on the “remote_host” machine. You can also specify the fully qualified path to the working directory where the hypervisor will store all of its generated files on the Dynamips host.

Note: you must use a DNS name or an IP address in the host text box.

“Base UDP” is the base port for UDP NIOs that Dynamips uses to make the connections between your nodes. Dynamips will use a UDP port for each end of a link. For example, six UDP ports are used for a full meshed lab of 3 routers and a base udp of 10000.

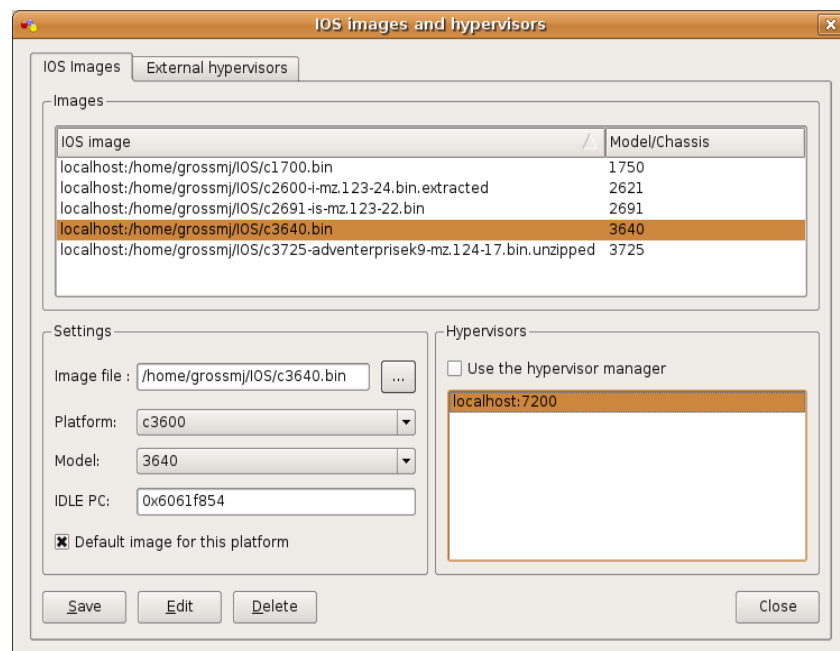
Here is an output of the netstat command that show you the connections between the nodes and the UDP port picked up by Dynamips:

```
udp    0    0 localhost:10000    localhost:10001    ESTABLISHED
udp    0    0 localhost:10001    localhost:10000    ESTABLISHED
udp    0    0 localhost:10002    localhost:10003    ESTABLISHED
udp    0    0 localhost:10003    localhost:10002    ESTABLISHED
udp    0    0 localhost:10004    localhost:10005    ESTABLISHED
udp    0    0 localhost:10005    localhost:10004    ESTABLISHED
```

Now let's imagine you want to run two connected IOS instances which are separately created on 2 different hypervisors on the same host and you choose the same UDP base for the hypervisors. Each hypervisor will try to take the same UDP port (10000 in the previous example) for each end of the connection and, of course, this will “collide” because Dynamips thinks they are different servers and therefore those UDP ports are safe to re-use.

“Base console” is the TCP base port that the hypervisor will use when you open a console on an IOS. This value shouldn't “collide” because GNS3 uses the following formula to affect a console port to each router: “base port” + router id (which is unique). So it is safe to let the same value for every hypervisor.

Once your hypervisors are recorded, you can bind them to your IOS images. Select your image, uncheck the “Use the hypervisor manager” option, and then choose your hypervisor in the list. Now every router that is configured with this IOS image is able to communicate with that hypervisor.



Note: be sure that any host-based firewalls running on all your Dynamips servers (for example, XP SP2's firewall) are permitting the necessary traffic. This includes the Dynamips server port (defaults to TCP 7200), the console ports (e.g. TCP 2000, 2001, ...) and the ports used by the NIO connections between interfaces, which start at UDP 10000 and work up from there.

Memory Usage Optimizations

As described in the [Resource Utilization](#) section, your labs can consume a large amount of real and virtual memory. The “ghostios” and “sparsemem” options were added to address both of these issues, respectively.

The Ghostios option can significantly reduce the amount of real host RAM needed for labs with multiple routers running the same IOS image. With this feature, instead of each virtual router storing an identical copy of IOS in its virtual RAM, the host will allocate one shared region of memory that they will all utilize. So for example, if you are running 10 routers all with the same IOS image, and that image is 60 MB in size you will save $9 \times 60 = 540$ MB of real RAM when running your lab. Enabling ghostios is as simple as checking a checkbox in the Dynamips preferences. This option is activated by default and applied to all router instances in the lab.

When enabled, you will notice additional files in the same directory as your router nvram files with names like “c3660-ik9o3s-mz.124-10.image.ghost”. This is the nmap’ed file that contains the shared memory region. The other files typically created with a router instance are created as well (log, nvram, and possibly bootflash files).

Measuring the amount of host memory saved with ghostios can be a little tricky due to the complexities of memory management in modern OSs. See [this sticky post](#) in the General section of [Hacki’s Forum](#) titled “Understanding memory usage and RAM Ghosting” for the gory details.

The “sparsemem” feature does not conserve real memory, but instead reduces the amount of virtual memory used by your router instances. This can be important, because OS limits a single process to 2 GB of virtual memory on 32-bit Windows, and 3 GB on 32-bit Linux. For example, on Windows, after the VM space is used by cygwin and other libraries dynamips depends on, this only leaves room for 4 router instances @ 256 MB each! Enabling sparsemem only allocates virtual memory on the host that is actually used by the IOS in that router instance, rather than the entire amount of RAM configured. This can allow you to run more instances per dynamips process before you have to resort to running multiple dynamips processes. See [this FAQ item](#) for more info on this issue.

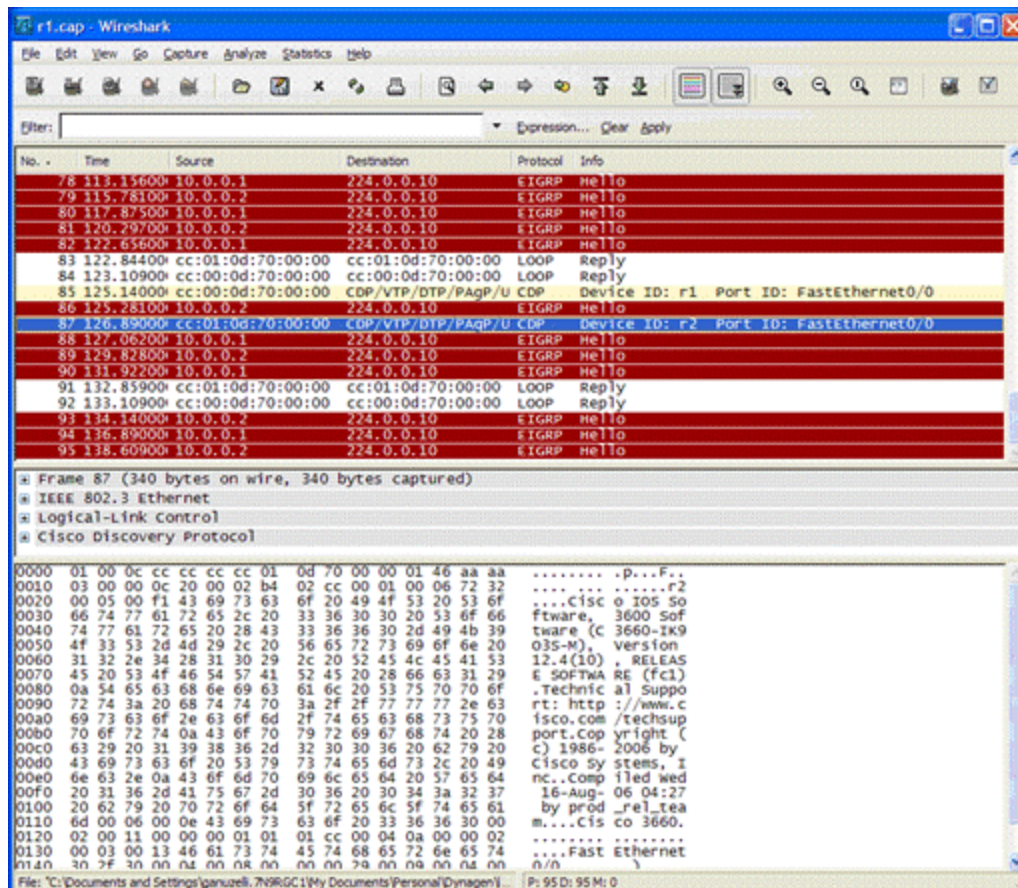
Packet Capture

Dynamips / GNS3 can capture packets on virtual Ethernet or Serial interfaces and write the output to a capture file for use with applications like [tcpdump](#), [Wireshark](#), or any other application that can read the libpcap capture file format.

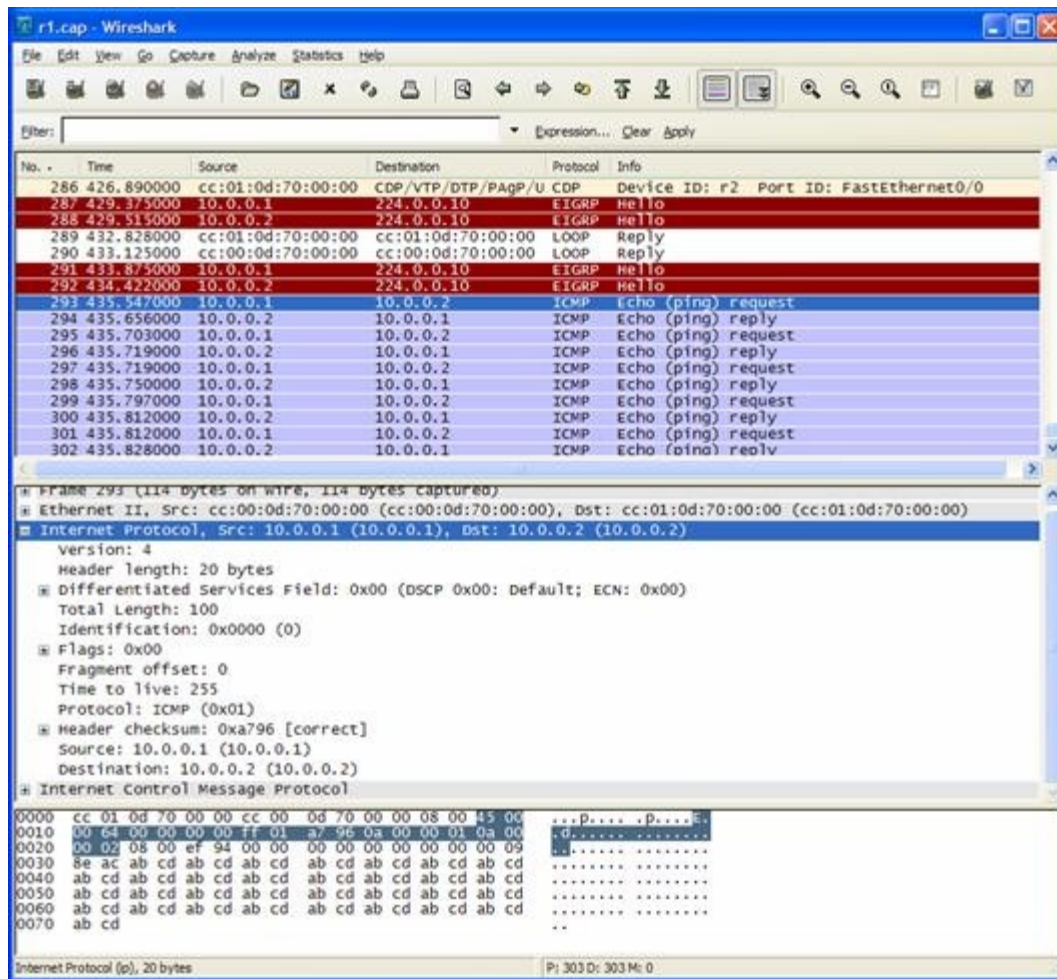
Consider three routers in series, “r1” and “r2” are connected via an Ethernet cable, and r2 connects to r3 via a point-to-point serial connection with HDLC encapsulation.

To begin capturing traffic at r1’s f0/0 interface and to write it to the file “r1.cap”, enter the following in the console window `capture r1 f0/0 r1.cap` or do a right-click on the link where you would like to capture the traffic (provided you configured capture preferences).

To view the traffic in real-time, open the file with Wireshark:



The capture is continuing to write packets to the output file. If we ping r2 from r1, then hit the “reload this capture file” icon we see:

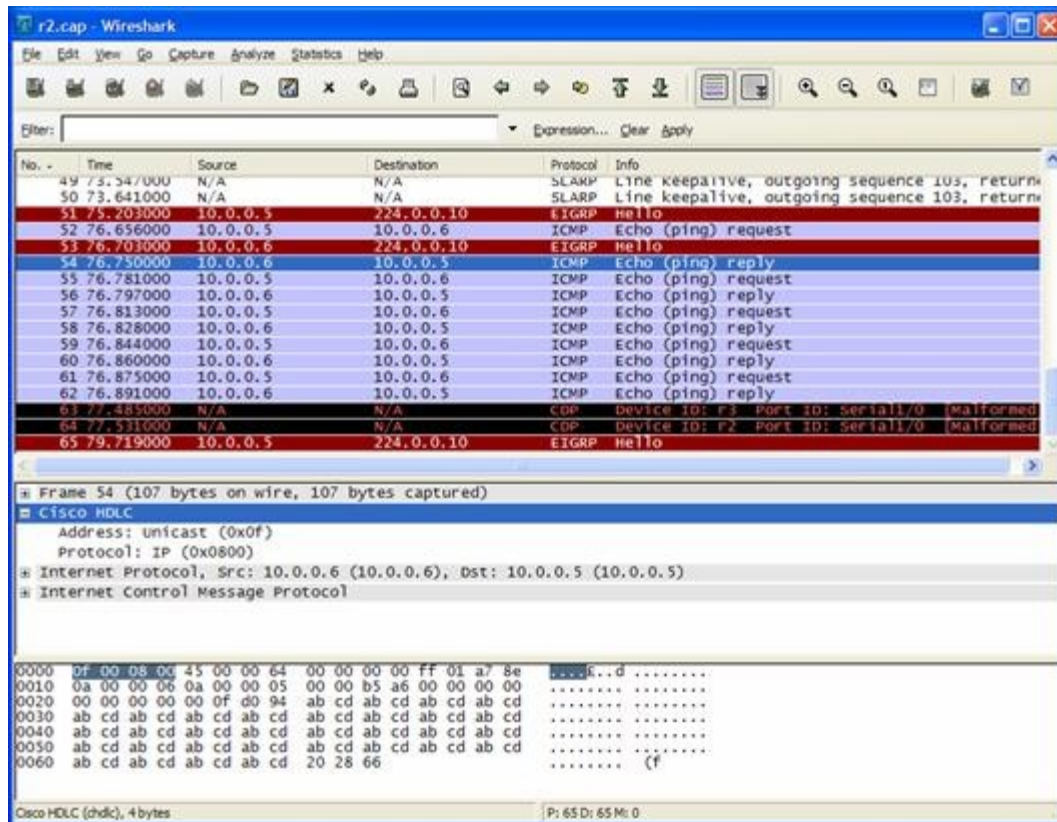


To stop capturing packets, enter `no capture r1 f0/0` or do a right-click on the link where you are capturing traffic.

Dynamips / GNS3 can capture packets at serial interfaces too. In this case we must also specify the encapsulation we are using on our routers, so Wireshark will know how to decode the packets. Our encapsulation options are FR (Frame-Relay), HDLC, or PPP. To capture some traffic on our HDLC encapsulated r2 to r3 link use:

```
capture r2 s1/0 r2.cap HDLC
```

Now we can open r2.cap, and the decode looks like this:

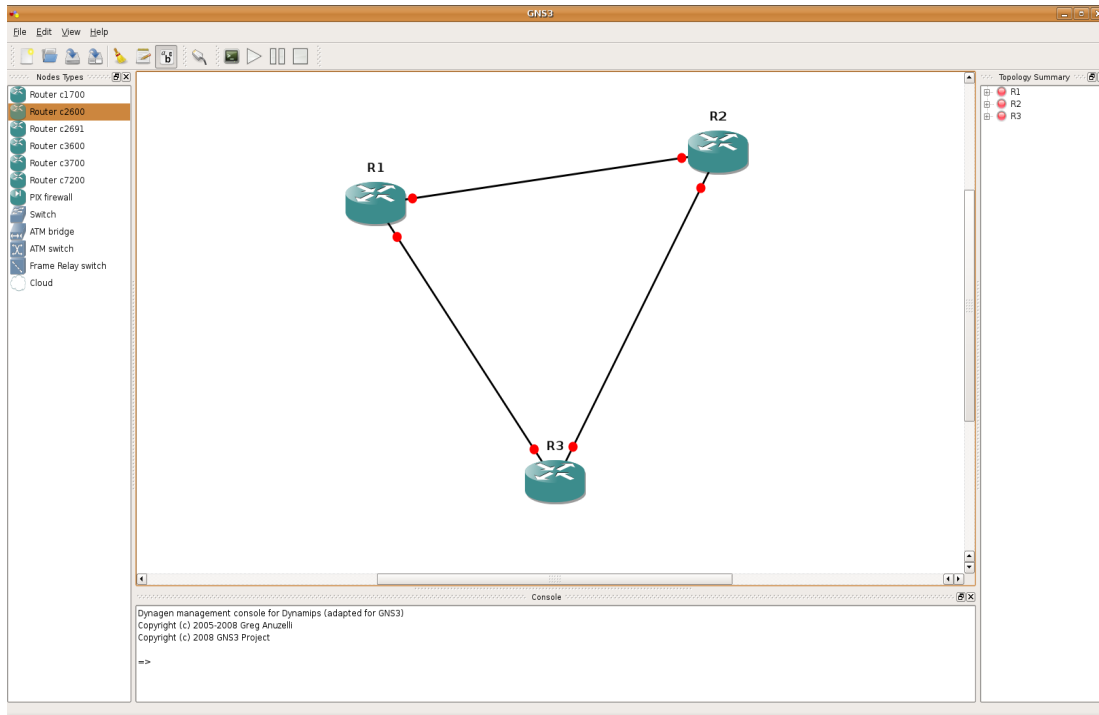


Now end the capture with “no capture r2 s1/0”. Note that you can have multiple captures running simultaneously against different interfaces on different routers.

Save and load a topology

GNS3 can save and load your network topologies in the Dynagen INI-like configuration format (.net extension). This means that you can use the same files for both GNS3 and Dynagen.

In the following example we created a topology of 3 routers (2610 chassis) and we saved it in emulation mode. A default IOS image for the 2610 chassis has been configured.



Here is the result saved in the .net file:

```
autostart = False
[localhost:7200]
workingdir = /tmp
[[2610]]
    image = /home/grossmj/IOS/c2600-i-mz.123-24.bin.extracted
    idlepc = 0x60bfa794
    ghostios = True
[[ROUTER R1]]
    model = 2610
    e0/0 = R3 e0/0
    slot1 = NM-4E
    e1/0 = R2 e1/0
    x = -197.549206511
    y = -164.192388155
[[ROUTER R2]]
    model = 2610
    e0/0 = R3 e1/0
    slot1 = NM-4E
    e1/0 = R1 e1/0
    x = 172.450793489
    y = -215.192388155
[[ROUTER R3]]
    model = 2610
    e0/0 = R1 e0/0
    slot1 = NM-4E
    e1/0 = R2 e0/0
    x = -3.54920651117
```

y = 111.807611845

You can now load this topology in Dynagen or GNS3.

Note: see Dynagen's tutorial to learn more about the .net file format.

Other Commands / Features

Here are some additional commands that can be used in the console that are not explained in this tutorial. Refer to the online help (*command* / ? or *help command*) for usage:

- **import / export** – Imports and exports router configs from nvram to text files on your host. Can be used to get a copy of your current configs, or as a “snapshotting” feature to save your router configs before you make changes.
- **push / save** – Much like import and export, but the configs are stored as base64 encoded “blobs” right in your network file (specified with the “configuration” option). This allows you to distribute an entire lab with the network topology and IOS configs all in a single .net file
- **filter** – Applies a connection filter to an interface. Currently the only filter supported by dynamips is “freq_drop”, which drops x out of every y packets across a link (simulating intermittent packet loss).
- **send** – Used to send raw hypervisor commands to dynamips (see README.hypervisor included with the dynamips source for documentation on hypervisor commands). These hypervisor commands are how GNS3 communicates with Dynamips. This command would typically only be used if developing new features in dynamips, experimenting, or simply curious.
- **ver** – outputs the version of Dynagen being used, as well as the versions of each dynamips instance Dynagen is connected to.
- **hist** – Console command history (like “history” in bash)

Also be sure to keep up on Dynamips development by following the technical blog at <http://www.ipflow.utc.fr/blog/> for the latest developments.

Hardware Currently Emulated

Borrowed from ggee's excellent post on Hacki's forum:

=====1700s=====

1710

Slots: 0 (available)

WIC slots: 0

CISCO1710-MB-1FE-1E (1 FastEthernet port and 1 Ethernet port, automatically used)

Note, interfaces do not use a slot designation (e.g. "f0")

1720

Note, interfaces do not use a slot designation (e.g. "f0")

1721

Note, interfaces do not use a slot designation (e.g. "f0")

1750

Note, interfaces do not use a slot designation (e.g. "f0")

1751

1760

Slots: 0 (available)

WIC slots: 2

C1700-MB-1ETH (1 FastEthernet port, automatically used)

Cards:

- WIC-1T (1 Serial port)

- WIC-2T (2 Serial ports)

- WIC-1ENET (1 Ethernet ports)

=====2600s=====

2610

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-1E (1 Ethernet port, automatically used)

2611

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-2E (2 Ethernet ports, automatically used)

2620

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-1FE (1 FastEthernet port, automatically used)

2621

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-2FE (2 FastEthernet ports, automatically used)

2610XM

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-1FE (1 FastEthernet port, automatically used)

2611XM

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-2FE (2 FastEthernet ports, automatically used)

2620XM

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-1FE (1 FastEthernet port, automatically used)

2621XM

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-2FE (2 FastEthernet ports, automatically used)

2650XM

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-1FE (1 FastEthernet port, automatically used)

2651XM

Slots: 1 (available)

WIC slots: 2

CISCO2600-MB-2FE (2 FastEthernet ports, automatically used)

Cards:

- NM-1E (Ethernet, 1 port)
- NM-4E (Ethernet, 4 ports)
- NM-1FE-TX (FastEthernet, 1 port)
- NM-16ESW (Ethernet switch module, 16 ports)
- NM-NAM
- NM-IDS
- WIC-1T (1 Serial port)
- WIC-2T (2 Serial ports)

=====3600s=====

3660

Slots: 6 (available)

3640

Slots: 4

3620

Slots: 2

Cards:

- NM-1E (Ethernet, 1 port)
- NM-4E (Ethernet, 4 ports)
- NM-1FE-TX (FastEthernet, 1 port)
- NM-16ESW (Ethernet switch module, 16 ports)
- NM-4T (Serial, 4 ports)
- Leopard-2FE (Cisco 3660 FastEthernet in slot 0, automatically used)

=====3700s=====

2691 (The 2691 is essentially a 3700 with 1 slot)

Slots: 1 (available)

WIC slots: 3

3725

Slots: 2 (available)

WIC slots: 3

3745

Slots: 4 (available)

WIC slots: 3

Cards:

- NM-1FE-TX (FastEthernet, 1 port)
- NM-4T (Serial, 4 ports)
- NM-16ESW (Ethernet switch module, 16 ports)
- GT96100-FE (2 integrated ports, automatically used)
- NM-NAM
- NM-IDS
- WIC-1T (1 Serial port)
- WIC-2T (2 Serial ports)

=====7200s=====

7206

Slots: 6 (available)

Chassis types:

- STD
- VXR

NPEs:

- NPE-100
- NPE-150
- NPE-175
- NPE-200
- NPE-225
- NPE-300
- NPE-400
- NPE-G2 (Requires the use of NPE-G2 IOS images)

Cards:

- C7200-IO-FE (FastEthernet, slot 0 only)
- C7200-IO-2FE (FastEthernet, 2 ports, slot 0 only)
- C7200-IO-GE (GigabitEthernet, slot 0 only)
- PA-FE-TX (FastEthernet)
- PA-2FE-TX (FastEthernet, 2 ports)
- PA-4E (Ethernet, 4 ports)
- PA-8E (Ethernet, 8 ports)
- PA-4T+ (Serial, 4 ports)
- PA-8T (Serial, 8 ports)
- PA-A1 (ATM)
- PA-POS-OC3 (POS)
- PA-GE (GigabitEthernet)

FAQs

How do I determine idle pc values from GNS3?

See the “Calculating Idle-PC” values section in this tutorial.

When I try to run more than 4 router instances @ 256 MB each (or 6 instances @ 160 MB each) on Windows, or more than 7 instances @ 256 MB each (or 11 instances @ 160 MB each) on 32-bit Linux Dynamips crashes.

This problem shouldn't occur if you used the Hypervisor Manager (used by default) with correct settings. This hypervisor is designed to “load-balance” your IOS instances on multiple Dynamips processes, but if you used hypervisors on your own on remote hosts, the problem is due to a per process memory limit.

By default, Windows has a 2 GB per process limit that (after including the memory used by the virtual router RAM, cygwin, libraries, and ‘scratch space’) that you are bumping up against. 32-bit Linux has a 3 GB per process limit by default.

The solution is to run multiple instances of Dynamips on the same system listening on different control ports like so:

On Windows:

```
start /belownormal /min "Dynamips" "dynamips.exe" -H 7200
```

```
start /belownormal /min "Dynamips" "dynamips.exe" -H 7201
```

On Linux/Unix:

```
nice dynamips -H 7200 &
```

```
nice dynamips -H 7201 &
```

Then correctly record those hypervisors in GNS3 (see Client / Server and Multi-server Operation)

I have a complex lab with several routers, and my serial interfaces are flapping, eigrp neighbor adjacencies are failing, show run and write mem takes forever.

This is most likely a performance issue with the host PC. Large labs consume lots of RAM and CPU. By default, the router's DRAM is simulated as a disk file of the same size as the allocated RAM. The host OS's caching features will naturally try to keep the most commonly access pages in RAM. But as your RAM runs low, disk thrashing will begin. The virtual routers then become "starved" for the CPU and start missing various hellos and such. There are several options for resolving this:

- Use a more powerful host (more RAM and / or a faster CPU)
- Distribute your lab across several hosts
- Use lower-end virtual routers where possible. For example, a 3620 running 12.2 IP base only needs 32 MB of RAM and could be used when you need to simulate a simple LAN router, or "the Internet".

There is a newer version of Dynamips available than the one bundled with the GNS3 Windows installer. How do I use it with GNS3 ? / How do I use GNS3 with Windows 2000 or Windows XP SP1?

The version of Dynamips included with the Windows GNS3 installer requires Windows XP SP2. In either of the above cases, download the Windows binaries from the

Dynamips site (<http://www.ipflow.utc.fr/blog/>). For Windows XP / 2003 use “dynamips-wxp.exe”. For Windows 2000, use the file “dynamips-w2000.exe” instead. Then copy both your executable and “cygwin1.dll” to “C:\Program Files\GNS3\Dynamips”, replacing the existing files.

On Linux / Unix / OS X, when I bridge a router or switch interface to my local host I can't ping it from my host. But this works on Windows? What gives?

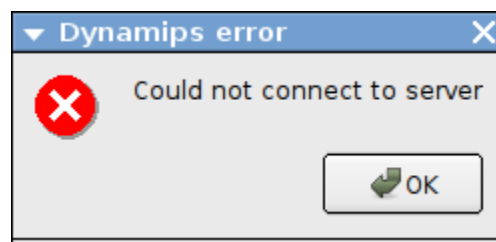
This does generally work on Windows (depending on your network card) but not on Linux / Unix. Most likely this is due to differences between libpcap and Winpcap, and the differences in the network stacks on Unix / Windows (e.g. NDIS). However, you should be able to ping your bridged interfaces from other systems on the bridged network. If this does not work on Windows for your particular NIC, try creating a Windows loopback adapter and bridging to that. See [this](#) thread for more info. On Linux you can use a tap interface and the NIO_tap NIO type. For OS X you can install tun/tap drivers as detailed in [this](#) thread.

Can I use GNS3 to make my network diagrams?

Yes but at the moment GNS3 only proposes symbols that are used in the emulation process, so you can make your diagrams with these symbols and export them as an image (jpeg, png, xpm, bmp are supported formats).

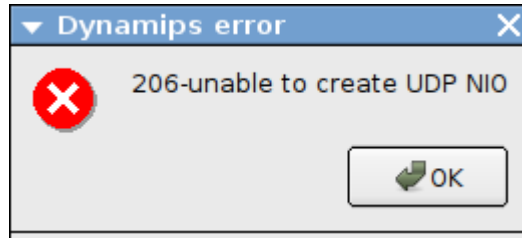
In a future release of GNS3, a package of decorative symbols will be provided.

I get Dynamips error message boxes but I don't know what is wrong?



If you have this error message, that means that the hypervisor is not listening, you should look at the hypervisor settings in the Dynamips preferences if you are using the hypervisor manager or at the hypervisors section in the “IOS images and hypervisors” window. If the problem persists you can try to:

- Start the hypervisor manually and see his output
- Check if you have not another Dynamips process running on your system
- Clean the working directory of Dynamips (especially any lock files)



This error message means that Dynamips can't create an UDP NIO, this is often due to a collision when choosing UDP ports, check your hypervisors settings and see the "Client / Server and Multi-server Operation" for more information.

***I have a question / I'm having a problem / I think I've found a bug.
How do I submit a quality post on the [forum](#) or the [bug tracking system](#) thereby increasing the likelihood that someone will be able to help me out?***

Be sure to note all the following in your post:

- The specific details of your issue
- Try to provide the simplest lab you can that recreates the issue
- Include the exception.log or exception_dynagen.log files if they exists.
- Any output from Dynamips (when using it externally)

Note: It is planned to provide a debug mode in a future release.